

## Coriolis Force

It is a fictitious force which appears to be acting on a particle moving with velocity  $\vec{v}$  with respect to observer connected to rotating frame.

We obtain relation connecting inertial acceleration of particle of mass  $m$  at  $P$  and its acceleration relative to rotating frame, we have

$$\left(\frac{dV_s}{dt}\right)_s = \left(\frac{dV_r}{dt}\right)_r + \omega \times V_s$$

Replacing  $V_s$  on right side we get

$$V_s = V_r + \omega \times r$$

$$\left(\frac{dV_s}{dt}\right)_s = \left(\frac{dV_r}{dt}\right)_r + \left(\frac{d(\omega \times r)}{dt}\right)_r + \omega \times V_r + \omega \times (\omega \times r)$$

$$= \left(\frac{dV_r}{dt}\right)_r + \left(\frac{d\omega \times r}{dt}\right)_r + \omega \times V_r + \omega \times V_r + \omega \times (\omega \times r)$$

When angular velocity is constant  $\left(\frac{d\omega}{dt}\right) = 0$

Then factor  $\left(\frac{dV_s}{dt}\right)_s$  is inertial acceleration  $a_s$

$\left(\frac{dV_r}{dt}\right)_r$  is acceleration  $a_r$

$$\therefore a_s = a_r + 2(\omega \times V_r) + \omega \times (\omega \times r)$$

Equation of motion in inertial system

$$F = ma_s$$

Multiplying  $m$

$$ma_s = ma_r + 2m(\omega \times V_r) + m\omega \times (\omega \times r)$$

$$F - 2m(\omega \times V_r) - m\omega \times (\omega \times r) = ma_r$$

To observer rotating system appears as particle is moving under effective force

$$F_{\text{eff}} = F - 2m(\omega \times v_r) - m\omega \times (\omega \times r)$$

Third term  $-m\omega \times (\omega \times r)$  is called centrifugal force.

$$|m\omega \times (\omega \times r)| = m r \omega^2 \sin \theta$$

$\theta$  is angle b/w  $\omega$  and  $r$

second term  $2m(\omega \times v_r)$  is called Coriolis force.

Directly proportional to  $v_r$  and will disappear when there is no motion.